

Group theory for physicists

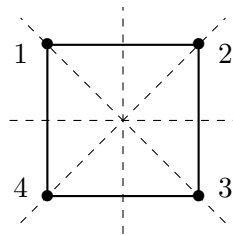
Problem set 3 (for the exercises in the week of Nov. 3)

Problem 1 Factor group

$H_2 = \{I, (123), (321)\}$ is an invariant subgroup of S_3 . It follows from the discussion in Sec. 1.8 of the lecture that S_3/H_2 is a group (the factor group). Use the multiplication law for cosets introduced in Sec. 1.8 to construct the multiplication table of the factor group and show that S_3/H_2 is isomorphic to $\mathbb{Z}_2$.

Problem 2 The group D_4

Consider the dihedral group D_4 , which is the symmetry group of the square, consisting of rotations around the center and reflections about the vertical, horizontal, and diagonal axes.



- Enumerate the group elements and construct the multiplication table.
- Find all classes.
- Find all nontrivial subgroups. Which of them are invariant?
- For all invariant subgroups H_i from part c), identify the factor group D_4/H_i (i.e., find the group to which D_4/H_i is isomorphic).
- Is the full group isomorphic to the direct product of some of its subgroups?

Problem 3 Homomorphism between $\text{Sl}(2, \mathbb{C})$ and the Lorentz group

Let $x = (x_0, x_1, x_2, x_3)$ be a four-vector in Minkowski space M . The space M is a 4-dimensional real vector space with metric $\|x\|^2 = x_0^2 - x_1^2 - x_2^2 - x_3^2$. A homogeneous Lorentz transformation Λ is a linear map from M to M that preserves the metric, i.e.,

$$\|\Lambda x\|^2 = \|x\|^2 \quad \text{for all } x \in M.$$

Such transformations form a group, the Lorentz group. Now identify every point in M with a Hermitian 2×2 matrix,

$$X = \begin{pmatrix} x_0 + x_3 & x_1 - ix_2 \\ x_1 + ix_2 & x_0 - x_3 \end{pmatrix}. \quad (1)$$

It is straightforward to show that $\det X = x_0^2 - x_1^2 - x_2^2 - x_3^2 = \|x\|^2$. The set of Hermitian 2×2 matrices is a 4-dimensional real vector space. A basis of this space is given by the identity $\mathbb{1}_2$

and the three Pauli matrices, i.e., Eq. (1) reads $X = x_0 \mathbb{1}_2 + x_1 \sigma^1 + x_2 \sigma^2 + x_3 \sigma^3$. Now let A be an arbitrary complex 2×2 matrix and define the action of A on X by

$$X \rightarrow AXA^\dagger.$$

Since X is related to x via Eq. (1), this induces an action of A on the four-vector x ,

$$x \rightarrow \varphi(A)x.$$

Because of $(AXA^\dagger)^\dagger = AXA^\dagger$ the matrix $AXA^\dagger$ is Hermitian, and thus $\varphi(A)x$ is again a real four-vector. Now let us restrict A to be an element of $\text{Sl}(2, \mathbb{C})$, the group of two-dimensional complex matrices with determinant equal to 1. Because of $\det(AXA^\dagger) = |\det A|^2 \det X$ we then have

$$\|\varphi(A)x\|^2 = \|x\|^2,$$

and hence $\varphi(A)$ corresponds to a Lorentz transformation. In fact, the map φ is a homomorphism between $\text{Sl}(2, \mathbb{C})$ and the Lorentz group because it preserves the group multiplication:

$$\begin{aligned} (AB)X(AB)^\dagger &= ABXB^\dagger A^\dagger = A(BXB^\dagger)A^\dagger \\ &\rightarrow \varphi(AB)x = \varphi(A)\varphi(B)x. \end{aligned}$$

a) Show that for the matrix

$$U_\theta = \begin{pmatrix} e^{-i\theta} & 0 \\ 0 & e^{i\theta} \end{pmatrix}$$

$\varphi(U_\theta)$ is a rotation about the x_3 -axis by an angle of 2θ .

b) Show that for the matrix

$$V_\alpha = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$$

$\varphi(V_\alpha)$ is a rotation about the x_2 -axis by an angle of 2α .

c) Show that for the matrix

$$M_r = \begin{pmatrix} r & 0 \\ 0 & \frac{1}{r} \end{pmatrix}$$

$\varphi(M_r)$ is a Lorentz boost in the x_3 -direction with parameter $2 \ln(r)$.

Hint: A Lorentz boost in the x_3 -direction with parameter t has the form

$$\begin{pmatrix} \cosh t & 0 & 0 & \sinh t \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \sinh t & 0 & 0 & \cosh t \end{pmatrix}.$$