

# Chapter 8. Molecular vibration, Infrared, and Raman activity

## 8.1 Molecular vibration: background

Group theory helps in finding the solution of the dynamical matrix for molecular vibrations. In general the Hamiltonian for a molecule reads:

$$H = \sum_{i=1}^{N_{el}} \frac{\hat{p}_i^2}{2m_e} + \sum_{\mu=1}^{N_{at}} \frac{\hat{p}_{\mu}^2}{2M_{\mu}} - \sum_{i\mu} \frac{e^2 Z_{\mu}}{4\pi\epsilon_0 |\hat{r}_i - \hat{R}_{\mu}|} + \sum_{i,j} \frac{e^2}{4\pi\epsilon_0 |\hat{r}_i - \hat{r}_j|} + \sum_{\mu\nu} \frac{e^2 Z_{\mu} Z_{\nu}}{4\pi\epsilon_0 |\hat{R}_{\mu} - \hat{R}_{\nu}|}$$

If now we do the Born-Oppenheimer approximation and we solve the (formidably complex) problem of  $N_{el}$  interacting electrons in presence of  $N_{at}$  nuclei fixed at positions  $\vec{R}_{\mu}$  we obtain, to start with, the  $E_g(\{\vec{R}_{\mu}\})$ , ground state electronic energy. The dynamic of the nuclei can be treated by the effective potential:

$$V(\{\vec{R}_{\mu}\}) = \sum_{\mu\nu} \frac{e^2 Z_{\mu} Z_{\nu}}{4\pi\epsilon_0 |\vec{R}_{\mu} - \vec{R}_{\nu}|} + E_g(\{\vec{R}_{\mu}\})$$

We are particularly interested into  $V(\{\vec{R}_{\mu}\})$  around the equilibrium coordinates  $\{\vec{R}_{\mu}^0\}$ . We take the zero of the energy at the potential minimum and expand  $V(\{\vec{R}_{\mu}\})$  in the displacements  $\vec{z}_{\mu} = \vec{R}_{\mu} - \vec{R}_{\mu}^0$ .

If now we introduce the generic coordinate index  $k=1 \dots 3N_{at}$

$$H = \sum_k \frac{1}{2} m_k \dot{\vec{z}}_k^2 + \sum_{k,l} \frac{1}{2} \frac{\partial^2 V}{\partial z_k \partial z_l} \Big|_{\vec{z}_k=0} \vec{z}_k \vec{z}_l \quad (*)$$

The first order expansion vanishes by definition since  $\vec{R}_\mu^0$  is an equilibrium configuration.

The hamiltonian (\*) becomes give rise to a  $(3N_{\text{at}} \times 3N_{\text{at}})$  secular equation. The roots of the secular equation are the eigenfrequencies  $\omega_K^2$  and the eigenvectors denote the normal modes. The standard procedure consists in

i) eliminating the mass:

$$q_k = \sqrt{m_k} \xi_k$$

ii) Turn into normal mode coordinates

$$q_k = \sum_K a_{kK} Q_K$$

$$V = \frac{1}{2} \sum_{\substack{k,l \\ K,L}} \left( \frac{\partial^2 V}{\partial q_k \partial q_l} \right) a_{kK} a_{lL} Q_K Q_L = \frac{1}{2} \sum_K \omega_K^2 Q_K^2$$

where  $a_{kK} = a_{Kk}^T = (a^{-1})_{Kk}$  since  $\frac{\partial^2 V}{\partial q_k \partial q_l}$  is real and symmetric.

and  $\omega_K^2$  and  $a_{kK}$  are linked by the relation

$$\sum_{k,l} (a^{-1})_{kK} \frac{\partial^2 V}{\partial q_k \partial q_l} a_{lL} = \omega_K^2 \delta_{KL}$$

Group theory helps in reducing  $\frac{\partial^2 V}{\partial q_k \partial q_l} \Big|_{\{q_n\}=0}$  into a

block diagonal form and in classifying the symmetry of the

normal modes.

## 8.2 Application of Group Theory to Molecular Vibrations

Group theory helps in the diagonalization of  $V_{kl} \equiv \frac{\partial^2 V}{\partial q_k \partial q_l}$ , in the classification of the normal modes and in determining their interaction with radiation. The fundamental idea:

The symmetry of the molecule is not changed by the normal modes. It follows that

$$\hat{P}_R f_k^{(i,\alpha)} = \sum_{k'=1}^{l_i} D^{(i)}(R)_{k'k} f_{k'}^{(i,\alpha)}$$

$i$  - representation

$\alpha$  - labels equal representations

$f_k$  - the eigenmode associated to the frequency  $\omega_k$   
( $f_{k'}$  eigenmode degenerate with  $f_k$ )

$D^{(i)}(R)$  - matrix representation of the eigenmode

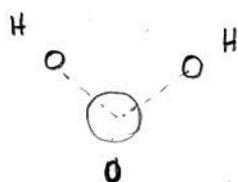
$R$  - operation  $\in G$ , the group of the Schrödinger equation

Notice,  $f_k$  (and  $f_{k'}$ ) is made of  $3N_{at}$  components!

The problem of finding the  $f_k$  is similar to the one of finding the eigenstates of the electronic Hamiltonian.

4)  $\Gamma_{\text{mol. vib.}}$  is expanded in terms of irreducible representations of  $G$ . With the help of the projection operator we can construct the  $f_k^{(i, \alpha)}$  starting from a "generic" atom displacement.

Example: the water molecule.



The point group of  $\text{H}_2\text{O}$  is  $C_{2v}$  since the molecule has a  $C_2$  symmetry axis and 2 vertical symmetry planes.

The character table

		E	$C_2$	$\sigma_v$	$\sigma_v'$
Z	$A_1$	1	1	1	1
$R_z$	$A_2$	1	1	-1	-1
$R_y, x$	$B_1$	1	-1	1	-1
$R_x, y$	$B_2$	1	-1	-1	1

$\rightarrow$  all atoms are sharing this symmetry plane.

$$\Gamma^{\text{a.s.}} = \left\{ \begin{array}{cc} 3 & 1 \\ \uparrow & \uparrow \\ & \text{number of atoms} \end{array} \begin{array}{cc} 3 & 1 \\ \uparrow & \uparrow \\ & \text{atoms} \end{array} \right\}$$

only O is invariant

$$\Gamma^{\text{a.s.}} = 2A_1 \oplus B_1 \quad \text{as can be easily checked.}$$

$$\Gamma^{\text{vec}} = A_1 \oplus B_1 \oplus B_2 \quad (\text{associated to } x, y, z)$$

$$\Gamma^{\text{rot}} = A_2 \oplus B_1 \oplus B_2 \quad (\text{ " " } R_x, R_y, R_z)$$

$$\Gamma_{\text{vib}} = (\Gamma^{\text{a.s.}} \otimes \Gamma_{\text{rec}}) - \Gamma_{\text{rec}} - \Gamma_{\text{rot}}$$

$$= (2A_1 \oplus B_1) \otimes (A_1 \oplus B_1 \oplus B_2) \ominus A_1 \ominus A_2 \ominus 2B_1 \ominus 2B_2$$

The product of (irreducible) representations has a character set which is the class by class product of the character sets:

$$\chi^{\Gamma_1 \otimes \Gamma_2}(C_k) = \chi^{\Gamma_1}(C_k) \chi^{\Gamma_2}(C_k)$$

The further decomposition of the representation follows the usual rules.

$$A_1 \otimes \Gamma = \Gamma \quad \forall \Gamma$$

$$B_1 \otimes B_1 = A_1$$

$$B_2 \otimes B_2 = A_2$$

$$\text{It follows that } \Gamma_{\text{vib}} = 2A_1 \oplus 2B_1 \oplus \cancel{2B_2} + B_1 \oplus A_1 \oplus \cancel{A_2} \\ \ominus A_1 \ominus \cancel{A_2} \ominus 2B_1 \ominus \cancel{2B_2} =$$

$$= \boxed{2A_1 \oplus B_1}$$

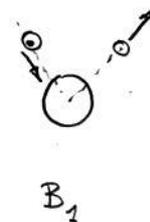
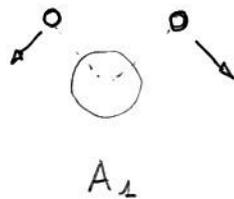
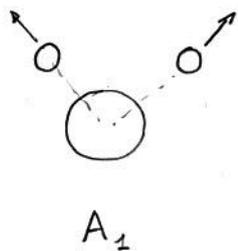
Since they are the three of them one dimensional representations, I can obtain the normal mode by application of the projector operator technique.

$$\vec{N}_{H_1} = \hat{e}_x + \hat{e}_y$$

$$\vec{N}_0 = \hat{e}_x + \hat{e}_y$$

$$\vec{N}_{H_2} = 0$$

A simple orthogonalization though:



where oxygen does not move. Notice that  $A_1$  modes are defined apart from an overall translation in the  $z$  direction and  $B_1$  modes apart from a  $x$  translation and a rotation around  $y$ . To obtain the "true" modes one should require no center of mass motion and  $L_y = 0$