

**Problem 1: Covectors**

Derive the transformation law for covector components from the definition  $dx^i(\partial_j) = \delta_j^i$  for the dual basis. Conclude that the evaluation  $w(v) = w_i v^i$  of a vector  $v$  using a covector  $w$  is independent on the choice of basis.

**Problem 2: Push forward and pull back**

Compute the coordinate expression for the pull back of a vector field along a diffeomorphism  $\Phi$  by using its inverse. Confirm that the evaluation of a vector  $v$  using a covector  $w$ ,  $w(v)$ , is invariant under pull backs, i.e.  $(\Phi_* w)(\Phi_* v) = w(v)$ . Show also that  $\Phi_* \Phi^* = \Phi^* \Phi_* = \text{Id}$ .

Hint:  $\delta_j^i = \frac{\partial x^i}{\partial x^j} = \frac{\partial(\Phi^{-1})^i(\Phi(x))}{\partial x^j} = \dots$

**Problem 3: Great circles**

Show that the shortest path between two points on a sphere is a section of a great circle by solving the geodesic equation in suitable coordinates.

**Problem 4: BONUS: Geodesic equation**

Derive the geodesic equation by varying the length functional

$$d(c) = \int_c ds := \int_c \sqrt{g_{ij} dx^i dx^j} := \int_a^b d\lambda \sqrt{g_{ij}(c(\lambda)) \frac{dx^i}{d\lambda} \frac{dx^j}{d\lambda}}$$

along a curve  $c : [a, b] \rightarrow \mathcal{M}_n$ . It is easiest to start with the case where the curve parameter  $\lambda$  measures proper length, so that

$$\sqrt{g_{ij}(c(\lambda)) \frac{dx^i}{d\lambda} \frac{dx^j}{d\lambda}} = \text{const}$$

as a function of  $\lambda$  along the desired trajectory. What corrections to the geodesic equation are necessary if  $\lambda$  does not measure proper length?