

Problem 1: Dirac bracket and choice of second class constraints

Show that the Dirac bracket is (weakly) unaffected by an alternative choice of second class constraints, $\chi'_\alpha = A_\alpha{}^\beta \chi_\beta$, where $\det A_\alpha{}^\beta \neq 0$.

Problem 2: Henneaux & Teitelboim: problem 1.21

Assume that the second-class constraints $\chi_\alpha = 0$ split as $\chi_\alpha \equiv (\gamma_a, C_a)$ where the subset $\gamma_a = 0$ is first class by itself, $\{\gamma_a, \gamma_b\} = C_{ab}{}^c \gamma_c$. Let F be an arbitrary phase space function. Prove the existence of an equivalent function $\bar{F} = F + \lambda^\alpha \chi_\alpha$, which is first class w.r.t. the γ_a , $\{\bar{F}, \gamma_a\} = f_a{}^b \gamma_b$. Show that the first-class system with constraints $\gamma_a = 0$ and Hamiltonian \bar{H} is equivalent to the original second-class system.

Problem 3: Henneaux & Teitelboim: problem 1.23

Consider the following system of second-class constraints

$$\chi_1 = 1 + q (e^{2qP-Q} + p + P^2) \quad (1)$$

$$\chi_2 = p + P^2 \quad (2)$$

where (q, p) and (Q, P) are conjugate pairs. Construct a first class system equivalent to it.

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Problem 4: Bonus exercise: Recursive Hamiltonians

- a) Warmup: Consider the Hamiltonian

$$H_0 = O(q^i, p_i, \mu), \quad (3)$$

with standard Poisson brackets $\{q^i, p_j\} = \delta_j^i$. μ is for now a fixed parameter constant on phase space. Compute the equations of motion.

- b) Next, consider the case when $\mu = f(O)$ is a function of the Hamiltonian. The Hamiltonian is then recursively defined as

$$H = O(q^i, p_i, f(O)). \quad (4)$$

Compute the equations of motion and relate the Hamiltonian vector field to that of H_0 .

- c) Try to rederive the equations of motion along the following lines. First, extend the phase space with the variables μ, p_μ , $\{\mu, p_\mu\} = 1$, then imposing the constraint $\Phi = \mu - f(O) \approx 0$, which Poisson commutes with the Hamiltonian. The new Hamiltonian is the total Hamiltonian $H_T = H_0 + \lambda\Phi$ for λ arbitrary. Choose a gauge fixing $p_\mu - h(q^i, p_j) \approx 0$ for Φ and determine λ by requiring stability of the gauge fixing. For which choices of h do you obtain the wanted equations of motion? Why is this not always the case?

Hint: It may be instructive to start with the simpler case $\mu = f(q^i, p_j)$, where f is independent of O .